Isolating restriction and exchange in gray matter using double and single diffusion encodings with equal diffusion weighting

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Synopsis

The diffusion MR signal in complex tissue such as gray matter exhibits non-Gaussian signal attenuation due to exchange and restrictions. Existing signal models typically ignore one or both effects by assuming Gaussian diffusion or negligible exchange. We propose a more rigorous signal model that incorporates both effects. Subsequently, an acquisition scheme utilizing equal double diffusion encodings ($b_1 = b_2$) at various mixing times, and single diffusion encodings with the same total weighting $b = b_1 + b_2$, is designed to independently characterize the effects of restriction and exchange. The method is tested on live and fixed gray matter specimen using a low-field, high-gradient MR system.

Introduction

Diffusion microstructural MR aims to probe tissue microstructure and extract parameters via signal models. For white matter, the field has conjectured a "standard model"^{1,2} consisting of water confined in myelinated axons and neurites, modelled as impermeable cylinders, and extra-cellular water presumed to undergo hindered, Gaussian diffusion – ignoring exchange. While this standard model and extensions thereof³ have been effective for understanding some features of white matter, they have failed to translate to gray matter,^{1,4,5} perhaps due to higher expected membrane permeabilities of gray matter components,^{6,7} e.g., astrocytes highly expressing aquaporin.⁸ In contrast, models of exchange such as the Kärger model⁹ typically exclude restriction and assume that signal components have different but otherwise Gaussian diffusivities.^{10,11} This assumption may underestimate exchange rates, as slower signal attenuation at high *b*-values is attributed to slower exchange, rather than non-Gaussian signal attenuation.

To advance the study of complex tissue using diffusion MR, we propose a rigorous signal model for certain experimental parameters that incorporates both restriction and exchange. With this model in mind, we design an acquisition scheme to characterize restriction and exchange independently. The method utilizes single and double diffusion encodings (S/DDEs) with equal total *b*-values to remove Gaussian diffusion. Diffusion exchange spectroscopy (DEXSY) measurements,¹² (i.e., DDEs with a storage time t_m) at a fixed *b*-value but varied t_m are then used to separate restriction and exchange. The method is tested on *ex vivo* neonatal mouse spinal cord (consisting mostly of gray matter¹³) using a permanent magnet system with a storog static gradient (SG).

Theory

Consider spin echoes formed under an SG with constant amplitude g and variable echo time 2τ . The regimes of signal behavior^{14,15} are associated with three length scales: (i) the diffusion length $\ell_d = \sqrt{D_0 \tau}$; (ii) the gradient dephasing length, $\ell_g = (D_0/\gamma g)^{1/3}$; and (iii) the structural length, or size of restriction in the gradient direction, ℓ_s . The free diffusion regime corresponds to ℓ_d being the shortest of ℓ_d , ℓ_g , ℓ_s ; diffusion is Gaussian, and the normalized echo intensity is $I/I_0 = \exp(-bD_0)$, where $b = (2/3)\gamma^2 g^2 \tau^3$. The motional averaging regime corresponds to ℓ_s being shortest. The localization regime – in which there may be persistent signal localized near boundaries – corresponds to ℓ_g being shortest. The signal attenuation in both non-Gaussian regimes is characterized by $I/I_0 \propto \exp(-b^{1/3})$ in the limit of large ℓ_d .¹⁶

For heterogeneous tissue, ℓ_s values may be distributed with a probability density function (PDF) $P(\ell_s)$ (see Fig. 1).¹⁷ When $\ell_d \gtrsim \ell_g$, the signal may be approximated as two signal fractions demarcated by ℓ_q , f_e ($\ell_s > \ell_q$), and f_m ($\ell_s \lesssim \ell_q$), corresponding to freely diffusing and motionally-averaged signal attenuating with¹⁸

$$I/I_0 \simeq \exp\left(-b^{1/3}\langle c
angle
ight), \quad \ell_d \gg 2\langle R
angle$$

$$\langle c
angle = rac{4}{175} rac{\gamma^{4/3} g^{4/3} \langle R^4
angle}{(2/3)^{1/3} D_0},$$
(1)

respectively, where $R = \ell_s/2$ is an effective spherical radius and $\langle \rangle$ denotes ensemble-averaging over $R = [0, \ell_g/2]$. Given that $\ell_d \gtrsim \ell_g$ and ignoring exchange during encodings and relaxation processes, I/I_0 for a DEXSY experiment becomes

$$\begin{split} \frac{I}{I_0} &= f_{m,m} \exp\left(-\left[b_1^{1/3} + b_2^{1/3}\right] \langle c \rangle\right) + f_{m,e} \exp\left(-b_1^{1/3} \langle c \rangle - b_2 D_0\right) \\ &+ f_{e,m} \exp\left(-b_1 D_0 - b_2^{1/3} \langle c \rangle\right) + f_{e,e} \exp\left(-[b_1 + b_2] D_0\right), \end{split}$$
(3)

where $f_m = f_{m,e} + f_{m,m}$ and f_m , f_e are exchanging fractions dependent on t_m . Applying the similarity transform to the sum $b_s = b_1 + b_2$ and difference $b_d = b_1 - b_2$ in *b*-values described in Refs.^{19,20,21} and taking a finite difference approximation of the *curvature* in I/I_0 w.r.t. b_d about $b_d = 0$ (fixing b_s), we remove the non-exchanging Gaussian diffusion contribution, and the exchanging fraction $f_{exch} = f_{m,e} + f_{e,m} = 2f_{m,e}$ (by mass balance) can be written as

$$f_{exch}(t_m) = \frac{2 \left[\Delta I(t_m) - \Delta I(t_m = 0) - f_m a_1 b_s^2\right]}{b_s^2 \left[a_0 \exp\left(-2^{-1/3} b_s^{1/3} \langle c \rangle - 2^{-1} b_s D_0\right) - a_1\right]}, \quad t_m > 0$$

$$= 2 f_m (1 - f_m) \left[1 - \exp\left(-t_m k\right)\right], \qquad (3)$$

where

$$\Delta I(t_m) = (I/I_0)\big|_{b_d = \pm b_s} - (I/I_0)\big|_{b_d = 0} \tag{4}$$

is the difference between equal DDEs ($b_d=0, b_1=b_2$) and SDEs with the same $b=b_s$,

$$a_{0} = \left(\frac{\langle c \rangle}{3\left[2^{1/3}b_{s}^{2/3}\right]} - \frac{D_{0}}{2}\right)^{2} + \frac{2^{2/3}\langle c \rangle}{9b_{s}^{5/3}}, \ a_{1} = \frac{\langle c \rangle}{18}\left(\frac{2}{b_{s}}\right)^{5/3}\exp\left(-2\left[\frac{b_{s}}{2}\right]^{1/3}\langle c \rangle\right), \tag{5}$$

and k is a first-order exchange rate.⁹ Restriction and exchange can be further separated by varying t_m . At small t_m (i.e., $t_m \ll 1/k$), $f_{exch} \approx 0$, such that ΔI depends only on f_m , $\langle c \rangle$,

$$\Delta I(b_s, t_m = 0) = f_m \left[\exp\left(-b_s^{1/3} \langle c \rangle\right) - \exp\left(-2^{2/3} b_s^{1/3} \langle c \rangle\right) \right]. \tag{6}$$

Eq. (6) can thus be fit for $f_m,\langle c
angle$, after which Eq. (3) can be fit for k (see Fig. 2).

Methods

DEXSY (SG-DEXSY) and double spin echo (SG-SE-SE) pulse sequences (Fig. 3) were implemented on a PM-10 NMR MOUSE single-sided magnet ($\omega_0 = 13.79 \text{ MHz}$, $B_0 = 0.3239 \text{ T}$, g = 15.3 T/m) with a home-built solenoid RF coil and test chamber. RF pulse lengths $= 2/2 \ \mu$ s, pulse powers = -22/-16 dB, TR = 2 s, 2000 or 8000 echo CPMG train with TE $= 25 \ \mu$ s, 8 points per echo, and 0.5 μ s dwell time. Normalization I_0 corresponds to $b = 0.089 \text{ ms}/\mu\text{m}^2$. Viable and fixed *ex vivo* neonatal (postnatal day 1-4) mouse spinal cords were studied. Spinal cords were bathed in artificial cerebrospinal fluid at 95% O₂/5% CO₂ and 25°C. More experimental details can be found in Refs.^{20,21} Curvature along b_d was assessed at $b_s = [0.3, 1, 6] \text{ ms}/\mu\text{m}^2$ on a viable spinal cord using both sequences. In addition, ΔI was assessed at $b_s = [2, 3, 3.5, 4, 4.5, 5, 6, 8, 10, 13, 20, 30, 60, 100] \text{ ms}/\mu\text{m}^2$ and $t_m = [0.2, 2, 10, 20, 160] \text{ ms}$ on a fixed spinal cord using the SG-DEXSY sequence.²⁰

Results

Increasing curvature depth with b_s is observed in viable spinal cord (Fig. 4). Exemplar plots of Eq. (6) are shown (Fig. 4B). SG-DEXSY data ($t_m = 0.2 \text{ ms}$) acquired on fixed spinal cord was fit to Eq. (6) using all b_s values or $b_s = [2, 3, 3.5, 4, 4.5, 5] \text{ ms}/\mu\text{m}^2$, corresponding to $1.37 \ell_g < \ell_d < 1.6 \ell_g$ (Fig. 5A). The truncated fit (i.e., whilst $\ell_d \gtrsim \ell_g$) is better and yields $f_m \approx 0.61$, $\langle c \rangle \approx 0.072 \ (\mu\text{m}^2/\text{ms})^{1/3}$. Fixing $b_s = 5 \text{ ms}/\mu\text{m}^2$, calculated $f_{exch}(t_m)$ values were fit to Eq. (3), yielding $k = 75 \text{ s}^{-1}$ (Figs. 5B–C).

Conclusion

Good fits are obtained to experimental data whilst $\ell_d \gtrsim \ell_g$, demonstrating the feasibility of the signal model and experimental approach. Apparent tissue parameters f_m , $\langle c \rangle$ characterizing restrictions similar to and smaller than $\ell_g = (D_0/\gamma g)^{1/3}$ and an exchange rate are measured. Approaches leveraging well-designed multidimensional (b_1, b_2, t_m) diffusion MR experiments may thus enable the isolation of restriction and exchange, though challenges remain in adapting such methods to high-field scanners.

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Figures



Fig. 1: Visualization of signal regimes.¹⁷ (A) The smallest of three length scales ℓ_d , ℓ_g , ℓ_s determines the regime. (B) Regimes when $\ell_d > \ell_g = 800 \text{ nm}$. $P(\ell_s)$ is a representative PDF. The motionally averaged sub-ensemble decays with characteristic $\langle \ell_s^4 \rangle$. (C) Regimes when $\ell_d < \ell_g$. We conjecture that exchange with first-order rate k occurs between free and non-Gaussian sub-ensembles. Note, for $\ell_d \gtrsim \ell_g$, little localized signal is expected.



Fig 2: Description of acquisition scheme. (A) Parameters are obtained in two steps. In the first step, ΔI is measured at various b_s (whilst satisfying $\ell_d \gtrsim \ell_g$) at t_m at or near zero to probe restriction. Signals are fit by non-linear least squares to yield f_m , $\langle c \rangle$. (B) In the second step, t_m is varied and b_s is fixed to probe exchange. Calculating $f_{exch}(t_m)$ and fitting to Eq. (3) yields k. Note, the steady-state exchange fraction at long t_m should agree with $2f_m(1-f_m)$. SG-DEXSY



Fig 3: Pulse sequences. Static gradient DEXSY (SG-DEXSY) and static gradient double spin echo (SG-SE-SE) pulse sequences implemented on a PM-10 NMR MOUSE single-sided system.



Fig. 4: Curvature along b_d for t_m near 0 measured on a viable *ex vivo* neonatal mouse spinal cord. (A) ΔI for the SG-DEXSY ($t_m = 0.2 \text{ ms}$) and SG-SE-SE pulse sequences at $b_s = [0.3, 1, 6] \text{ ms}\mu\text{m}^2$. Error bars ± 1 SD. (B) ΔI , measured as the difference between the endpoint(s) and the minimum, plotted vs. b_s . ΔI is consistent across sequences. Exemplar plots of Eq. (6) using $\langle c \rangle = 0.07 \ (\mu\text{m}^2/\text{ms})^{1/3}$ are shown. Fitting yields $f_m \approx 0.37$.



Fig 5: Acquisition scheme tested on data from fixed spinal cord. (A) ΔI measured using SG-DEXSY ($t_m = 0.2 \text{ ms}$). Error bars $= \pm 1$ SD. Truncated fit to Eq. (3) (red) compared to fit using all b_s values (blue). The truncated fit yields the parameters shown. (B) ΔI at various t_m . (C) $f_{exch}(t_m)$ calculated from (B), fixing b_s and using data in (A) for the $\Delta I(t_m = 0)$ term in Eq. (3). Fitting yields $k = 75 \text{ s}^{-1}$. The steady-state fraction agrees with $2f_m(1 - f_m)$ from (A).

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